

# Assignment 2

A)

- a) Response time for circuit with simple regulation is 0.693147 s.  
Response time for circuit with negative autoregulation is 0.248914 s.

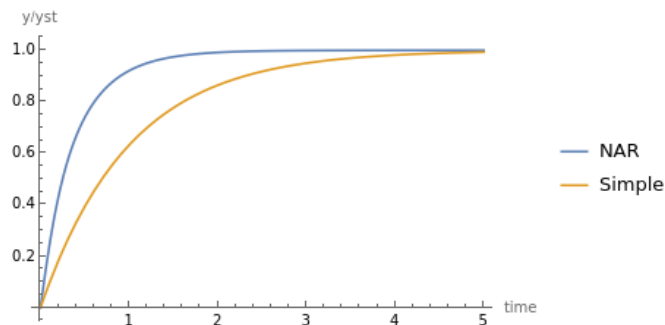
Note: Our goal is to have same steady state concentration for both NAR and simple regulatory circuit.

Code:

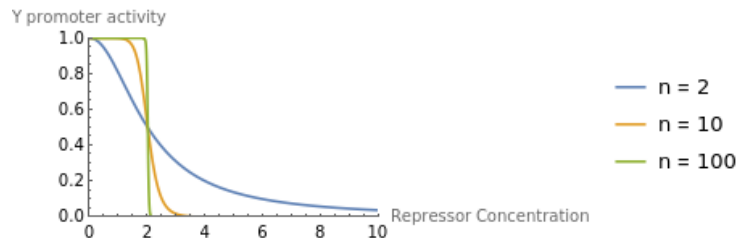
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params = {β → 1, k → 0.3, α → 1, n → 2}
solNAR = NDSolve[{y'[t] == β / (1 + (y[t] / k)^ n) - α y[t], y[0] == 0.00} /. params, y, {t, 0, 5}]
yStNAR = y[t] /. solNAR
yStSimple = y[t] /. NSolve[{0 == β / (1 + (y[t] / k)^ n) - α y[t] && y[t] > 0} /. params, y[t]]
params = Insert[params, βsimple → yStNAR [[1]], -1]
solS = DSolve[{y'[t] == βsimple - α y[t], y[0] == 0} /. params, y, {t, 0, 5}]
yStSimple = y[t] /. solS
NSolve[{0 == βsimple - α y[t] && y[t] > 0} /. params, y[t]]
p1 = Plot[{(y[t] /. solNAR) / yStNAR, (y[t] /. solS) / yStSimple}, {t, 0, 5}, PlotRange → All,
PlotLegends → {"NAR", "Simple"}, AxesLabel → {"time", "y/ySt"}]
tSimp = t /. NSolve[{y[t] == yStSimple / 2} /. solS, t]
tNAR = t /. NSolve[{y[t] == yStNAR / 2} /. solNAR, t]

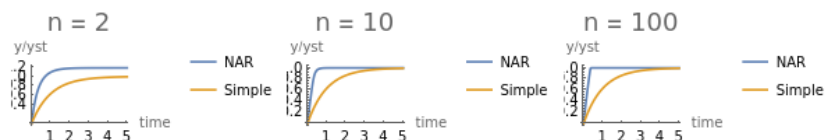
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- b) We will have to increase  $n$  (cooperativity) in hill function to reach the limit of step function of inhibition.



With the increase in  $n$ , we observe even faster initial growth and lower delay in auto repression to stop production at the desired steady-state.



- c) Given,  $\beta_{NAR} = 2,20,200 \mu\text{M}/\text{h}$  and  $n \rightarrow \infty$ . Now since  $y[t] \ll \beta_{NAR}/\alpha$ , we can approximate  $T_{1/2}^{NAR} = K/2\beta_{NAR}$ . Response time of simple regulatory circuit is  $T_{1/2}^{simple} = \ln 2/\alpha$

$$\Rightarrow T_{\frac{1}{2}}^{NAR} = 0.3 \frac{\mu\text{M}}{2 * 2,20,200 \mu\text{M h}^{-1}} = 6.81 * 10^{-7} \text{ h}$$

And,

$$T_{1/2}^{simple} = \frac{\ln 2}{1 \text{ h}^{-1}} = 0.693 \text{ h}$$

- d) At the step function limit i.e.  $n \rightarrow \infty$  and  $y[t] \ll \beta_{NAR}/\alpha$ , we know  $T_{1/2}^{NAR} = K/2\beta_{NAR}$  and  $T_{1/2}^{simple} = \ln 2/\alpha$ . This means  $T_{1/2}^{NAR}$  does not depend on  $\alpha$ , while  $T_{1/2}^{simple}$  is inversely proportional to  $\alpha$ .

- e) Using the above mentioned formulas, we calculate  $T_{1/2}^{NAR}$  and  $T_{1/2}^{simple}$ .

$\alpha$	$T_{1/2}^{NAR}$ (hr)	$T_{1/2}^{simple}$ (hr)
1	0.005	0.693
2	0.005	0.346
10	0.005	0.069
20	0.005	0.034

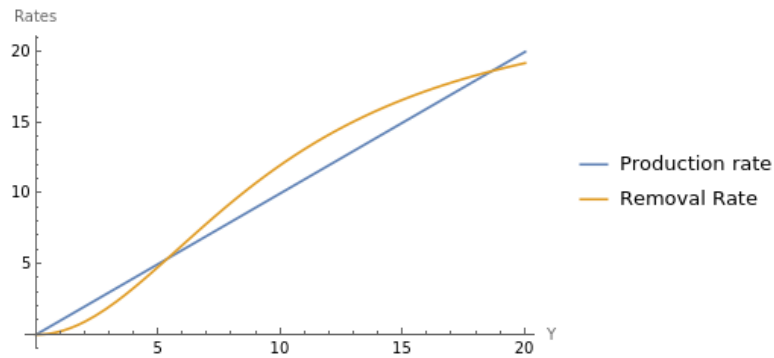
- f) Summary statement:

- Response time of NAR circuit depends on half – saturation constant  $k$  and maximal production rate  $\beta$ .
- Response time of simple regulatory circuit depends on removal rate  $\alpha$ .
- Steady state concentration of NAR circuit depends on half – saturation constant  $k$ .
- Steady state concentration of simple regulatory circuit depends on maximal production rate  $\beta_{simple}$  and removal rate  $\alpha$ .

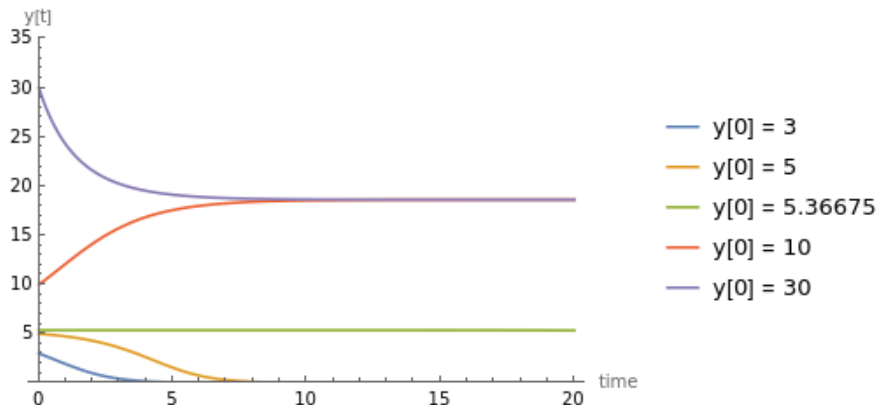
B)

- a) Steady state concentration of  $y$  given  $y[0] = 0 \mu M$  is  $0 \mu M$ .  
 Steady state concentration of  $y$  given  $y[0] = 30 \mu M$  is  $18.6332 \mu M$ .

The given PAR circuit has three fixed points ( $y = 0 \mu M$ ,  $y = 5.36675 \mu M$  and  $y = 18.6332 \mu M$ ). The fixed point  $y = 5.36675 \mu M$  is unstable, thus steady state concentration of  $y$  is either  $0 \mu M$  or  $18.6332 \mu M$  which depends on initial conditions.



- b) Critical concentration at which the systems switches from the OFF state to the ON state is  $y = 5.37775 \mu M$ .



Code:

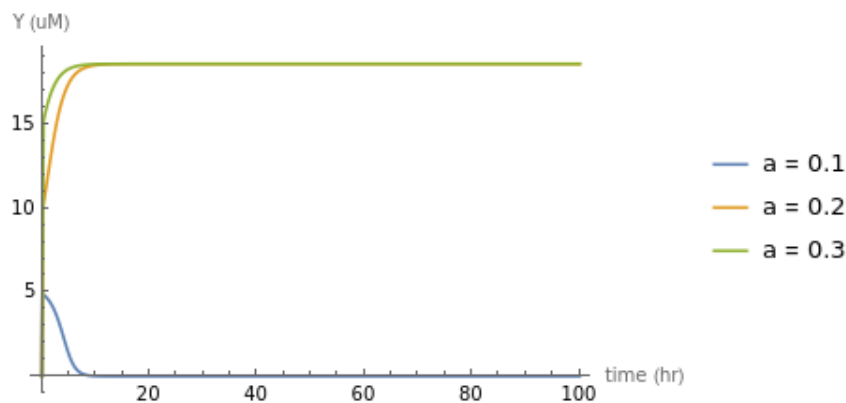
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params = {  $\beta \rightarrow 24$ ,  $k \rightarrow 10$ ,  $\alpha \rightarrow 1$ ,  $n \rightarrow 2$  }
solPAR1 = NDSolve [{ $y'[t] == \beta ((y[t] / k)^n) / (1 + (y[t] / k)^n) - \alpha y[t]$ ,  $y[0] == 3$ } /. params ,
y, {t, 0, 20}]
solPAR2 = NDSolve [{ $y'[t] == \beta ((y[t] / k)^n) / (1 + (y[t] / k)^n) - \alpha y[t]$ ,  $y[0] == 5$ } /. params ,
y, {t, 0, 20}]
solPAR3 = NDSolve [{ $y'[t] == \beta ((y[t] / k)^n) / (1 + (y[t] / k)^n) - \alpha y[t]$ ,  $y[0] == 10$ } /. params ,
y, {t, 0, 20}]
solPAR4 = NDSolve [{ $y'[t] == \beta ((y[t] / k)^n) / (1 + (y[t] / k)^n) - \alpha y[t]$ ,  $y[0] == 30$ } /. params ,
y, {t, 0, 20}]
solPAR5 = NDSolve [{ $y'[t] == \beta ((y[t] / k)^n) / (1 + (y[t] / k)^n) - \alpha y[t]$ ,  $y[0] == 5.36675$ } /.
params , y, {t, 0, 20}]

```

Plot[{y[t] /. solPAR1, y[t] /. solPAR2, y[t] /. solPAR5, y[t] /. solPAR3, y[t] /. solPAR4}, {t, 0, 20}, PlotRange → {All, {0, 35}}, AxesLabel → {"time", "y[t]"}, PlotLegends → {"y[0] = 3", "y[0] = 5", "y[0] = 5.36675", "y[0] = 10", "y[0] = 30"}]

- c) System has three steady-states and only two of them are stable.
- $y = 0 \mu M$ , *stable steady state*.
  - $y = 5.36675 \mu M$ , *unstable steady state*.
  - $y = 18.6332 \mu M$ , *stable steady state*.
- d) The steady-state concentration of Y after the pulse of production is gone depends on the duration of the pulse. If the pulse duration  $\leq 0.10$  hr then the steady state concentration is 0 and if pulse duration  $\geq 0.20$  hr then steady state concentration of Y is  $18.6332 \mu M$ .



Note: a is the duration of the pulse in hr.

Pulse duration to switch the steady state from  $0 \mu M$  to  $18.6332 \mu M$  has to be approximately greater than or equal to 0.2 hrs, which is evident from the above graph.

Code:

```
params = {  $\beta \rightarrow 24$ ,  $k \rightarrow 10$ ,  $\alpha \rightarrow 1$ ,  $n \rightarrow 2$  }
p[t] = UnitStep[t] - UnitStep[t - r]
```

```
sol = solPAR = ParametricNDSolve [ {y'[t] == 50 * p[t] +  $\beta$  ((y[t] / k)^n) / (1 + (y[t] / k)^n) -  $\alpha$  y[t], y[0] == 0} /. params, y, {t, 0, 200}, {r}]
Plot[Evaluate [Table[y[a][t] /. sol, {a, 0.1, 0.3, .1}], {t, 0, 100}, PlotRange → All, PlotRange → {All, {0, 50}}, AxesLabel → {"time (hr)", "Y (uM)"}, PlotLegends → {"a = 0.1", "a = 0.2", "a = 0.3"}]
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C)

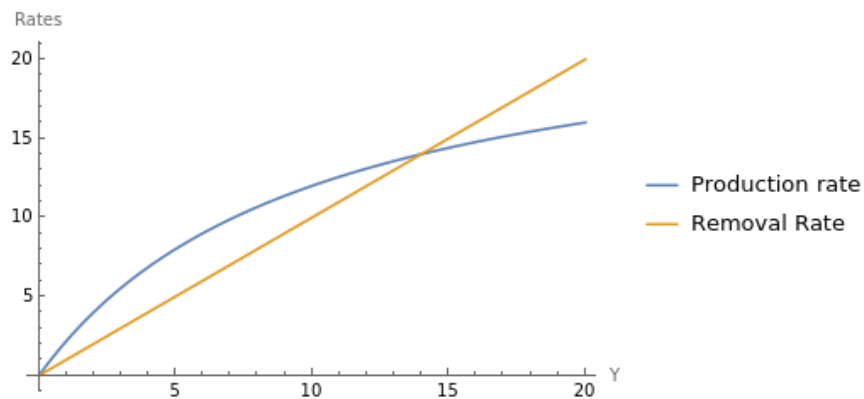
$$\frac{dy}{dt} = \beta \frac{y}{k + y} - \alpha * y$$

a) On fixed points  $\frac{dy}{dt} = 0$ .

$$\begin{aligned} \frac{dy}{dt} &= \beta \frac{y}{k + y} - \alpha * y = 0 \\ \Rightarrow y &= 0, y = \frac{\beta}{\alpha} - k \end{aligned}$$

Systems has two fixed points  $y = 0$  and  $y = \frac{\beta}{\alpha} - k$ .

b) System is monostable as fixed point  $y = \frac{\beta}{\alpha} - k$  is stable while fixed point  $y = 0$  is unstable.  
Fixed point  $y = \frac{\beta}{\alpha} - k$  is stable, because shifting  $y$  to either side (of  $\frac{\beta}{\alpha} - k$ ) causes a return to the fixed point.



Code:

```
Plot[{24*y/(y+10), y}, {y, 0, 20}, PlotLegends->{"Production rate", "Removal Rate"},  
AxesLabel -> {"Y", "Rates"}]
```