

Assignment 2

A. Negative auto-regulation

- a. Calculate the response time of a circuit with negative auto-regulation and compare it to the corresponding simple regulation circuit (that reaches the same steady state). Use the following parameters:

half-saturation constant $k = 0.3 \mu\text{M}$
maximal production rate $\beta = 1 \mu\text{M/h}$
Hill coefficient $n = 2$
degradation rate $\alpha = 1/h$

The following block of code provides you with a starting point for simulating simple regulation (solS) and NAR (solNAR) in Mathematica. It is the same model as you used in exercise 1B, except that the production rate is now a Hill function of Y as we discussed in the lectures.

Hint: Take function that calculates $y[t]/y_{st}$ (e.g., $(y[t]/\text{solNAR})/y_{st\text{NAR}}$) and ask at what time t this function reaches 0.5 using the Solve[] function, and solving for t .

```
params = {β->1, k->0.3, α->1, n->2}
solNAR = NDSolve[{y'[t] == β 1/(1+(y[t]/k)^n)-α y[t],
y[0]==0.00} /.params, y, {t,0,5}]
solS = NDSolve[{y'[t] == β -α y[t], y[0]==0} /.params, y, {t,0,5}]
yStNAR = y[t] /. NSolve[{0==β 1/(1+(y[t]/k)^n)-α y[t] && y[t]>0} /.params, y[t]]
yStS = β/α /.params
Plot[{(y[t] /. solNAR) / yStNAR, (y[t] /. solS) / yStS}, {t,0,5}, PlotRange->All,
PlotLegends ->{"NAR", "Simple"}, AxesLabel ->{"time", "y/ySt"}]
```

- b. Which parameter do you have to change to reach the limit of a step function of inhibition discussed in the lecture? Change the parameter accordingly and simulate the dynamics. What qualitative difference do you observe in the shape of the dynamics?
- c. Calculate the response time of NAR and simple regulation by finding the time t where $y[t]$ reaches half of its steady-state. Choose the same parameters as in 1b at the step function limit. Then change the maximal production rate to be 2, 20, 200 $\mu\text{M/h}$. You can do this either numerically with the model above, or algebraically using the equation derived in the lecture.
- d. Calculate how the response time of NAR and of simple regulation change with respect to the removal rate. To do so, use parameters close to the step-function limit and use the following parameters:
- maximal production rate $\beta \rightarrow 100 \mu\text{M/h}$
half – saturation constant $k \rightarrow 1 \mu\text{M}$
- e. How does the response time of NAR and simple regulation change with the removal rate α being 1, 2, 10, 20 h^{-1} ? The response time of which regulation is more affected by the removal rate: simple regulation or NAR? You can do this either numerically with the model above, or algebraically using the equation derived in the lecture.
- f. Make a summary statement: Which parameter determines the response time of an NAR circuit (at the step-function limit) and which one determines the response time under simple

regulation? Which parameter determines the steady-state of the NAR and of the simple regulation circuit?

B. Positive autoregulation

Simulate a circuit with positive auto-regulation with parameters

$$\beta \rightarrow 24 \frac{\mu\text{M}}{\text{h}}, k \rightarrow 10 \mu\text{M}, \alpha \rightarrow 1/\text{h}, n \rightarrow 2.$$

Using the following code:

```
params = {  $\beta$ ->24, k->10,  $\alpha$ ->1, n->2 }
```

```
solPAR = NDSolve[{y'[t] ==  $\beta$  ((y[t]/k)^n) / (1+(y[t]/k)^n) -  $\alpha$  y[t],  
y[0]==3} /. params, y, {t, 0, 200}]
```

```
Plot[y[t] /. solPAR, {t, 0, 200}, PlotRange->{All, {0, 35}}, AxesLabel->{"time", "y[t]"}]
```

```
y[200] /. solPAR
```

```
yStPAR = y[t] /. NSolve[{0 ==  $\beta$  ((y[t]/k)^n) / (1+(y[t]/k)^n) -  $\alpha$  y[t] && y[t] >= 0} /. params, y[t]]
```

- Determine the steady-state when starting from the OFF state ($y[0] = 0 \mu\text{M}$). Now simulate the steady state when starting from an ON state ($y[0] = 30 \mu\text{M}$). How are these different?
- Change the starting conditions continuously. What is the critical concentration at which the systems switches from the OFF state to the ON state?
- How many steady-states does the system have? How many are stable?
- A cell has been in the OFF state for a long time. Now, it gets a pulse of signal such that the production rate of Y increases transiently by $\Delta\beta = 50 \mu\text{M}/\text{h}$. Subsequently the Signal disappears again ($\Delta\beta = 0$). What is the steady-state concentration of Y after the pulse of production is gone? How long (how many hours or minutes) does the pulse have to be for the steady-state to switch?

Hint: Use the same parameters as for exercises a-c and change the equation in the model to accommodate the $50 \mu\text{M}/\text{h}$ increase in production rate, then find time t where the concentration of y passes the switching point.

C. Positive autoregulation without cooperativity

No computer needed for this exercise.

Exercise B models a positive auto-regulation with a Hill coefficient of $n=2$. Write down the corresponding model with a Hill coefficient of $n = 1$.

- How many fixpoints does the circuit have?
- Is the system mono- or bi-stable? Explain using a graph of production and removal rates as a function of the concentration of y how you reach your conclusion.